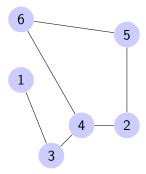
Intro to Graph Theory 2014 IOI Camp 1

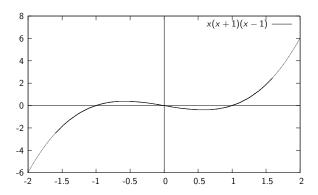
Robert Spencer

December 11, 2013

This is a graph:



This is not a graph:



Definition

A graph is a collection of *nodes* connected by *edges* which may or may not be *directed* and/or *weighted*

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Examples of graphs:

- A computer network (non-directed, non-weighted)
- A road map (non-directed, weighted)
- Winners in a chess tournament (directed, non-weighted)
- Payments in an economy (weighted, directed)

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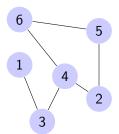
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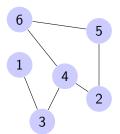
Can you find a path and a cycle?



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Can you find a path and a cycle?



Example Answer:

Path: 1-3-4-2

Cycle: 4-2-5-6-4

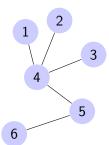
Definition

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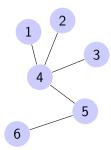
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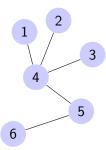
Theorem

A tree of n vertices has n-1 edges.

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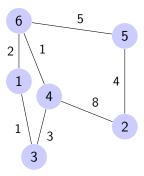
Theorem

A tree of n vertices has n-1 edges.

Proof.

Induction. Start with one vertex, and add subsequent ones.

Weights are placed on edges, and can represent anything (lengths, costs, etc.)



Graph Representations

How do we represent a graph?

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Lists of Neighbours

```
[(3,1),(6,2)]
```

Memory O(E)

Graph Representations

How do we represent a graph?

Lists of Neighbours

[(5,5)]

Memory O(E)

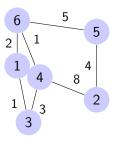
Adjacency Matrix

$$\begin{pmatrix} 0 & 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 8 & 4 & 0 \\ 1 & 0 & 0 & 3 & 0 & 0 \\ 0 & 8 & 3 & 0 & 0 & 1 \\ 0 & 4 & 0 & 0 & 0 & 5 \\ 0 & 0 & 0 & 1 & 5 & 0 \end{pmatrix}$$

Memory $O(N^2)$

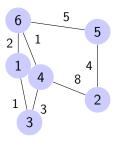
Traversal

Sometimes we want to visit all the nodes in a graph in a particular order. For example to search for a path/destination



Traversal

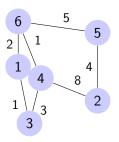
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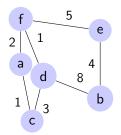


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Often this is used to find the shortest route between two or more nodes.

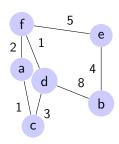
Depth First Search (DFS) visits the nodes as far as it can before backtracking (without visiting nodes more than once).

Sample Graph:



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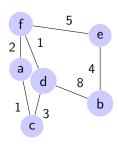


Psudocode:

def DFS(currNode, finalNode)
 if currNode==finalNode then
 return success
 set currNode visited
 foreach neighbour of currNode do
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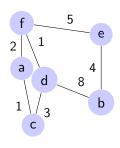
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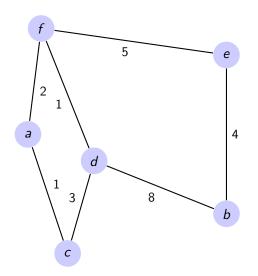
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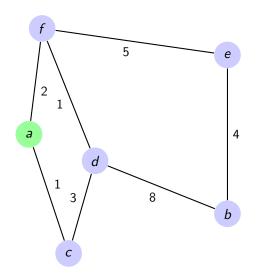


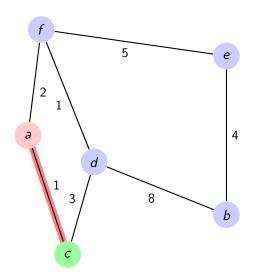
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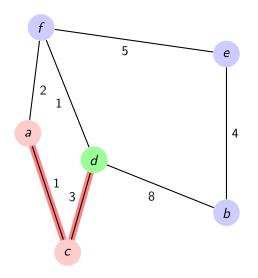
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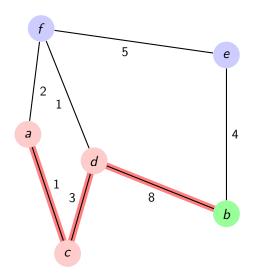
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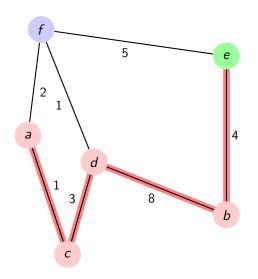


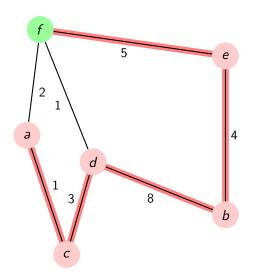


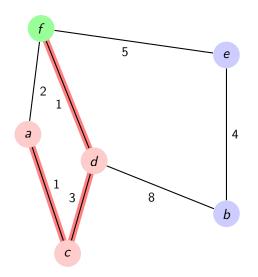


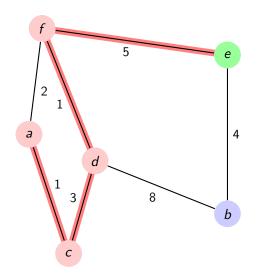


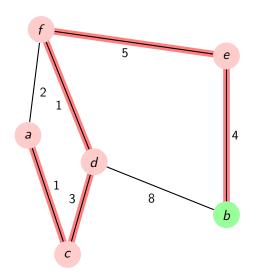


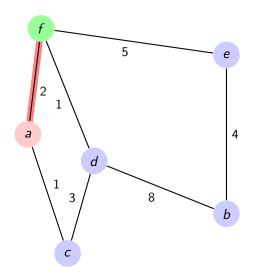


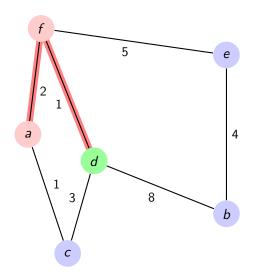


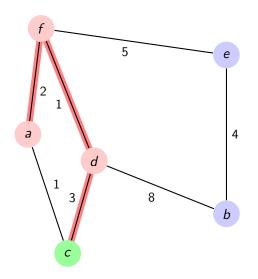


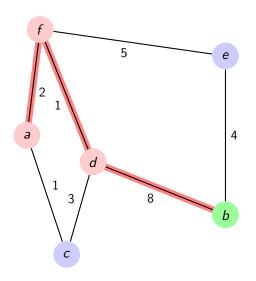


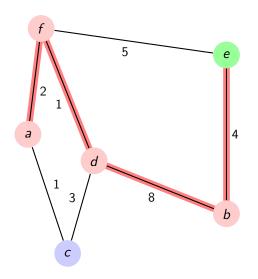






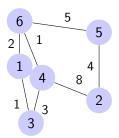






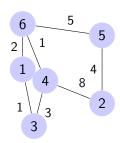
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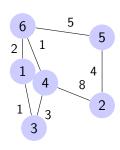


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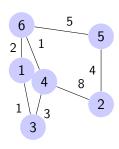
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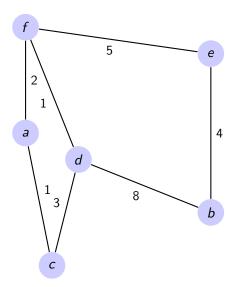
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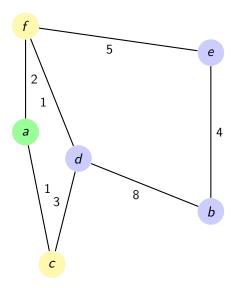


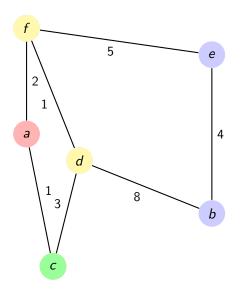
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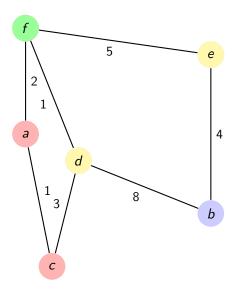
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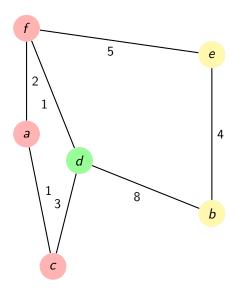
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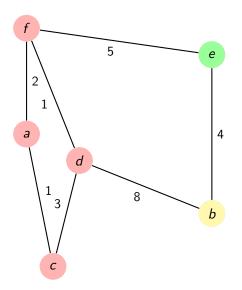


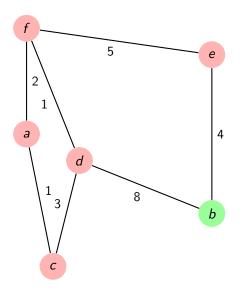












Dijkstra's Algorithm

Dijkstra's Algorithm finds the shortest distance from one node to all others. It is basically a BFS with a priority queue.

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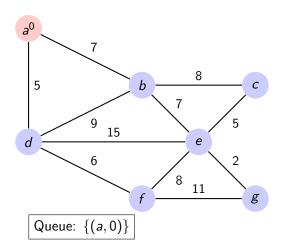
```
set all distances INF
add (0, startNode) to queue
while queue not empty do
   currDists,currNode = queue.pop
   distances[currNode] = currDist
   for neighbour,distance in adjacent[currNode] do
     possNewDist = distances[currNode] + distance
   if distances[neighbour] > possNewDist then
     update neighbour to weight possNewDist in queue
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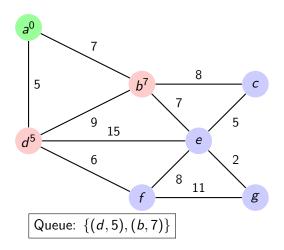
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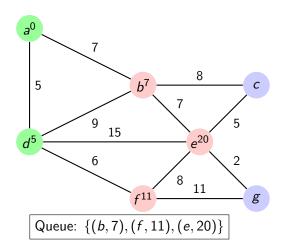
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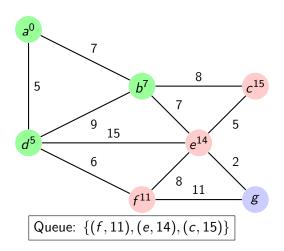
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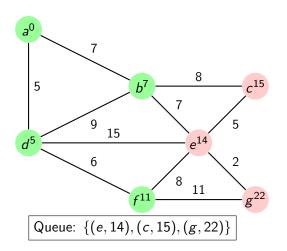
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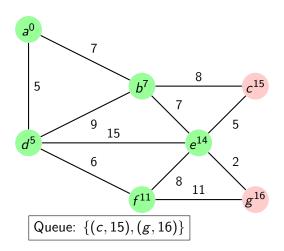


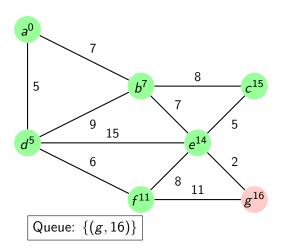


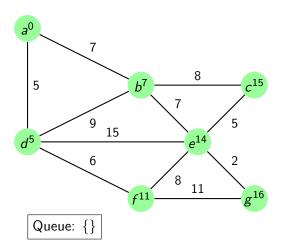








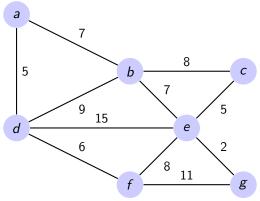




Minimum Spanning Tree

Definition

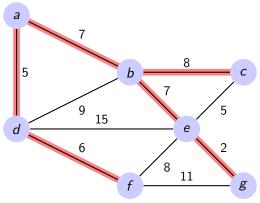
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Algorithm

- Set all vertices to "not in the tree" except a starting vertex.
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Prim's Algorithm

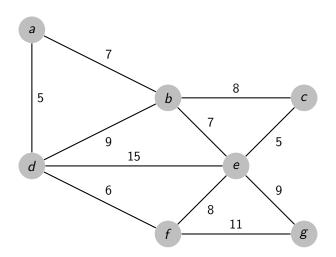
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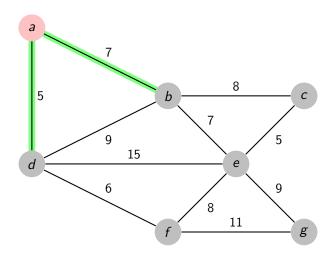
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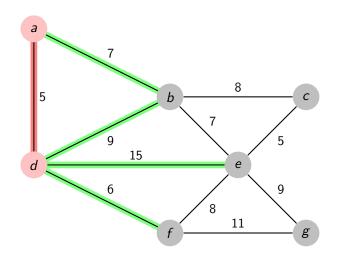
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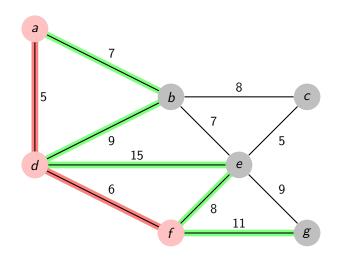
Technical notes

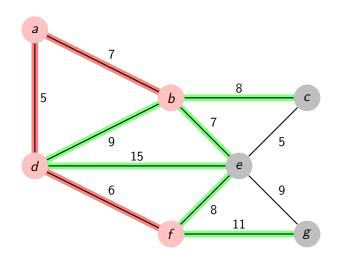
- Keep a priority queue of edges. Each step pull off an edge, check if it joins a new vertex. If it does, add all the edges from that vertex to the queue.
- Runs in $O(E \log V)$ with a binary heap as priority queue.

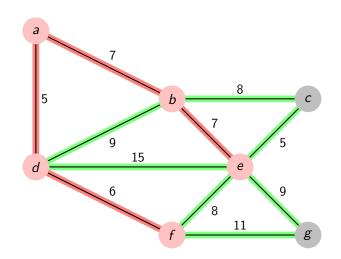


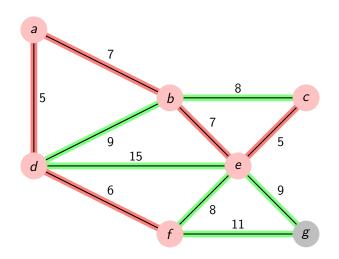


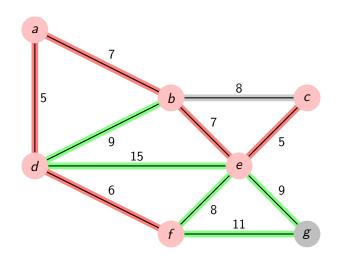


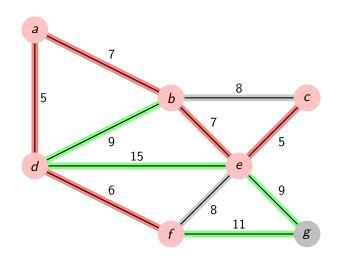


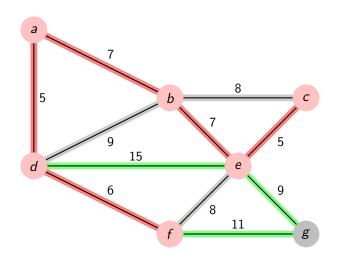


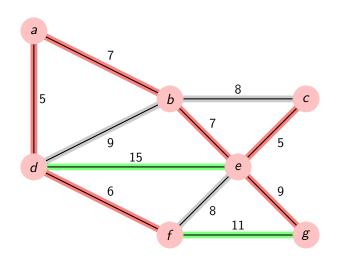


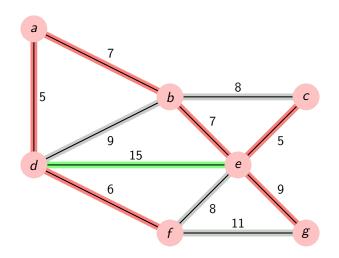


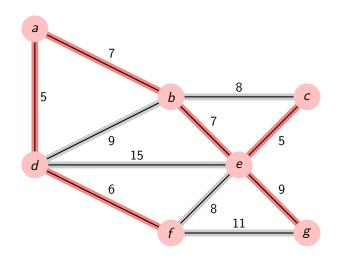












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Technical Notes:

- Use "union-find" to hold the different trees.
- Complexity $O(E \log E)$



